FANUC	FANUC America Corporation 3900 West Hamlin Road Rochester Hills, Michigan 48309-3253 TSL@fanucrobotics.com	_ Document ID:	Quick Reference Document [Page 1 of ]  Document ID: How to INIT Start from the Startupconfig file Rev 3  Date: 03/28/22 Robot Models Supported: R-30iB Plus and Mate Plus			
1-800- <i>i</i> Q-ROBOT		Rev: <b>0</b> Reference:	Init: KTB	Software Required		

#### **FANUC America Corporation Quick Reference Document**

Here is the information you requested!

Note: This short document was compiled at your request as a courtesy of the FANUC America Technical Support Group.

For detailed information, you should consult your FANUC America technical manual.

For more information, call our Hotline: 1800-iQ-ROBOT

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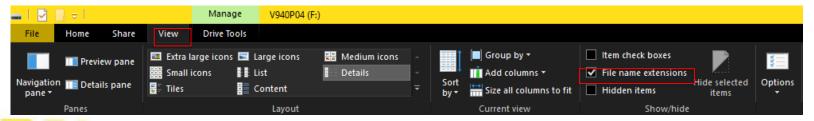
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<sup>\*</sup> Note: This document is provided as a courtesy and contains condensed and/or summarized information tailored to assist you with a specific issue. For additional and/or detailed information, you must refer to the appropriate FANUC America Corporation Manual or eDoc which specifically applies to the robotics system(s) at your location.

## INIT Start from Startupconfig.XML

- 1) Create new blank file called "startupconfig.xml" on a blank USB thumb drive.
- 2) Place USB thumb drive in controller door UD1:, turn controller on. Wait 1 minute.
- 3) Remove USB and place it back in your PC
- 4) Turn the controller back off
- 5) On the USB thumb drive, you will find a new file called "EXAMPLE.XML" that has a time-sensitive boot key
- 6) "STARTUPCONFIG.XML" could be renamed to "OLDSTARTUPCONFIG.XML"

NOTE: you may need to make sure file name extensions are visible in Windows Explorer



#### **EXAMPLE.XML**

- Open the file EXAMPLE.XML, it contains several different commands for different systems operations that can be done.
- Time-sensitive boot key is on line 3, it is valid for one hour.
- For INIT Start, the only line you will need (other than the header) is line 11

### Create STARTUPCONFIG.XML

```
<?xml version="1.0" encoding="utf-8"?>
 <CONTROLLER expires = "03/28/2022 - 17:56:02" key = "b0359e63-57eb2cbc">
 FULL - personality - 0:Existing Personality
 RESTORE - dcsparam - 0:Do not load DCS from SRAM 1:None/Default:Load DCS from SRAM
Note: Four different CONFIGs shown. If multiple CONFIGs are used, only the last valid CONFIG will be processed.
<CONFIG startmod = "full" personality = "1"/>
<CONFIG image = "UD1:\IMG\" startmod = "restore" dcsparam = "1" />
<CONFIG image = "UD1:\IMG\" startmod = "backup"/>
                                                                                                                                                          <ROOT>
<CONFIG startmod = "init"/>
<ETHERNET id ='port1' label='CD38A' ip = "DHCP"/>
<ETHERNET id ='port2' label='CD38B' ip = "172.168.192.10" router = "172.168.1.1" mask = "255.255.240.0" hostname = "MY_ROBOT" />
                                                                                                                                                            </CONTROLLER>
<ETHERNET id ='port3' label='CD38C' ip = "192.168.192.10" router = "192.168.1.1" mask = "255.255.255.0" />
                                                                                                                                                          </ROOT>
<PENDANT ip = "172.168.192.200" />
<STARTMODE value = "COLD" />
<COMMAND exec = "UD1:\PSDATA1.CF"/>
 </controller>
```

</ROOT>

In the Example.XML file, delete all the unnecessary lines so only the ones on the right remain

# Create STARTUPCONFIG.XML

Startupconfig.xml contents

- Use 'Save As' to rename your new "EXAMPLE.XML" file to "STARTUPCONFIG.XML"
- Save it on the USB thumb drive.
- Insert USB thumb drive into controller door UD1: and power on the controller.
- WAIT at least 7 minutes for the INIT Start to finish, usually the LED on the thumb drive will stop flashing when it is done, but be sure to wait at least 7 minutes before powering down.
- Your controller is now initialized or Factory reset. You should now be able to establish communication with the HAAS CNC.